

respectively. It is seen that the thermal wave velocity and damping in a zinc crystal depend weakly on the propagation direction.

Thus, a characteristic singularity of acceleration wave propagation in an anisotropic medium is the deviation of the wave tubes from the normal vector. For $\tau = 0$ a second quasi-longitudinal wave appears which damps out more rapidly than the first. The relaxation time τ turns out to exert substantial influence on the nature of quasi-longitudinal and quasi-transverse wave propagation.

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ON DYNAMIC EFFECTS IN AN ELASTIC HALF-SPACE UNDER "THERMAL IMPACT"

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The general uncoupled dynamical problem of thermoelasticity for a half-space under the condition of a thermal impact with a finite rate of change in temperature on its boundary is solved by the method of principal (fundamental) functions within the framework of a generalized theory of heat conduction.

An elastic steel half-space is analyzed as an illustration. The problem on thermal stresses originating in an elastic half-space due to thermal impact produced by a jump change in temperature on the boundary was first analyzed in [1]. Since the temperature change on the boundary occurs at a finite rate, it is gene-

rally impossible to realize the thermal impact considered in [1] physically. The dynamic effects in an elastic half-space under a thermal impact with finite rate of change in the temperature on the boundary have been studied in [2]. For high rates of change of the heat flux we obtain a generalized wave equation of heat conduction [3] taking into account the finite velocity of heat propagation. Hence, the solution of the ordinary parabolic heat conduction equation used in [1, 2] does not correspond to the true temperature field. The problems of [1, 2] have been examined in [4, 5], respectively, within the framework of a generalized theory of heat conduction.

1. Formulation of the problem. Let an elastic half-space $z \geq 0$, as well as the medium in the domain $z < 0$ be initially at the temperature $t_0 = 0$, and then let the temperature of the medium adjoining the surface of the half-space $z = 0$ grow linearly from $t_0 = 0$ and reach the finite value α_0 within a small, but nonzero, time interval τ_0 . For $\tau > 0$ convective heat exchange according to Newton law occurs between the surface and the medium.

To determine the temperature field in this case it is required to find a bounded, sufficiently smooth solution of the problem

$$\begin{aligned} \frac{1}{w_r^2} \frac{\partial^2 t}{\partial \tau^2} + \frac{\bar{c}\gamma}{\lambda} \frac{\partial t}{\partial \tau} &= \frac{\partial^2 t}{\partial z^2}, \quad t|_{\tau=0} = 0, \quad \frac{\partial t}{\partial \tau} \Big|_{\tau=0} = 0 \quad (1.1) \\ \left[\frac{\partial t}{\partial z} - h \left(1 + \tau_r \frac{\partial}{\partial \tau} \right) (t - t_c) \right] \Big|_{z=0} &= 0, \quad \lim_{z \rightarrow \infty} t(\tau, z) = 0 \\ t_c|_{z=0} = \varphi(z) &= \begin{cases} 0, & \tau_0 \leq \tau \leq 0 \\ \alpha_0 \tau / \tau_0 & 0 \leq \tau \leq \tau_0 \\ \alpha_0 & \tau_0 \leq \tau \end{cases} \\ \tau &= \alpha_0 \frac{\tau}{\tau_0} J_-(\tau_0 - \tau) J_-(\tau) + \alpha_0 J_-(\tau - \tau_0) \end{aligned}$$

Here $J_-(s)$ is an asymmetric unit Heaviside function [6]. If it is now considered that the half-space was initially stress-free and that there are not stresses on its surface $z = 0$ during heating, then the problem [2]

$$\begin{aligned} \frac{\partial^2 \sigma_z}{\partial z^2} - \frac{1}{c^2} \frac{\partial^2 \sigma_z}{\partial \tau^2} &= a \frac{\partial^2 t}{\partial \tau^2}, \quad a = \frac{1 + \mu}{1 - \mu} \gamma \alpha_\tau \quad (1.2) \\ \sigma_z(\tau, z)|_{\tau=0} &= 0, \quad \frac{\partial \sigma_z}{\partial \tau} \Big|_{\tau=0} = 0, \quad \sigma_z|_{z=0} = 0, \quad \sigma_z|_{z=\infty} = 0 \end{aligned}$$

must be solved to determine the stresses. Here τ_r is the relaxation time of the thermal process, w_r is as yet a large, but finite velocity of heat propagation, λ is the coefficient of heat conduction, c is the specific heat of the substance, γ is the density of the substance, h is the relative coefficient of heat exchange, α_τ is the coefficient of linear expansion of the material, a is the speed of sound, and μ is a Lamé constant.

2. Mixed problem for the wave equation. Let us consider the problem of finding a sufficiently smooth solution bounded at infinity for the problem

$$\begin{aligned} L[u] \equiv b_0^2 \frac{\partial^2 u}{\partial \tau^2} + b_1^2 \frac{\partial u}{\partial \tau} - \frac{\partial^2 u}{\partial z^2} &= f(\tau, z) \quad (2.1) \\ u|_{\tau=0} = \varphi_1(z), \quad \frac{\partial u}{\partial \tau} \Big|_{\tau=0} &= \varphi_2(z) \end{aligned}$$

$$\begin{aligned}
 B[u]|_{z=0} &\equiv \left[\frac{\partial}{\partial z} - \alpha h \left(1 + \frac{\tau_r}{\beta} \frac{\partial}{\partial \tau} \right) \right] u \Big|_{z=0} = \\
 &- h \left(1 + \frac{\alpha}{\beta} \tau_r \frac{\partial}{\partial \tau} \right) u_c \equiv -h\psi(\tau) \\
 \lim_{z \rightarrow \infty} u(\tau, z) &= 0
 \end{aligned}$$

in the domain

$$\Pi^+ = \{(z, \tau); 0 \leq z < \infty, 0 \leq \tau \leq T (T \leq \infty)\} \equiv [0, \infty) \times [0, T$$

Definitions. (1). We call the function $K(\tau, z, \xi)$ satisfying the equation $L[u] = 0$ and the conditions

$$K|_{\tau=0} = 0, \quad \frac{\partial K}{\partial \tau} \Big|_{\tau=0} = \delta_z, \quad B[K]|_{z=0} = 0$$

the Cauchy function of the mixed problem (2.1).

(2). We call the function $W(\tau, s, z)$ satisfying the equation $L[u] = 0$, zero initial conditions, and the boundary condition

$$B[W]|_{z=0} = \delta_s$$

the Green's function of the mixed problem (2.1).

(3). We call the function $E(z, \xi, \tau, s)$ satisfying the equation

$$L[E] = \delta(z - \xi, \tau - s) = \delta(z - \xi) \otimes \delta(\tau - s) = \delta_z \otimes \delta_s$$

zero initial and boundary conditions the fundamental function of the mixed problem (2.1). Here δ_a denotes the Dirac measure concentrated at the point a and \otimes is the tensor product of the generalized functions.

Following [7], it can be verified that the functions K, W and E are

$$\begin{aligned}
 K(\tau, z, \xi) &= b_0^2 \left[\Phi(\tau, |z - \xi|) - \right. \\
 &\left. \Phi(\tau, z + \xi) - 2 \int_0^\infty \exp(-h_1 y) \frac{\partial}{\partial \xi} \Phi(\tau - \beta_1 y, z + \xi + y) dy \right] \\
 W(\tau, s, z) &= 2 \int_0^\infty \exp(-h_1 y) \frac{\partial}{\partial z} \Phi(\tau - s - \beta_1 y, z + y) dy \\
 E(z, \xi; \tau, s) &= \begin{cases} 0, & \tau \leq s \\ b_0^{-2} K(\tau - s; z, \xi), & \tau > s \end{cases} \\
 k_1 = \frac{b_1^2}{2b_0^2}, \quad h_1 = \alpha h, \quad \beta_1 = \beta^{-1} \alpha h \tau_r, \quad \Phi(\tau, z) &= b_0^{-2} G(\tau, z). \\
 G(\tau, z) &= \frac{1}{2} b_0 \exp(-k_1 \tau) I_0(k_1 \sqrt{\tau^2 - b_0^2 z^2}) J_-(\tau - b_0 z)
 \end{aligned}$$

where $G(\tau, z)$ is a fundamental solution of the Cauchy problem for the equation $L[u] = 0$. Compliance with the complement condition

$$\begin{aligned}
 h_1 + \beta_1 p + \sqrt{b_0^2 p^2 + b_1^2 p} &\neq 0 \\
 p = p_0 + ip_1, \quad p_0 > 0, \quad -\infty < p_1 < +\infty
 \end{aligned}$$

plays an essential part here.

Theorem. If the complement condition is satisfied, then the solution of the mixed problem (2.1) is determined by the formula

$$\begin{aligned}
 u(\tau, z) = & \exp(-k_1\tau) \left[\frac{b_0 - \beta_1}{b_0 + \beta_1} \varphi_1 \left(\frac{\tau - b_0 z}{b_0} \right) J_-(\tau - b_0 z) + \right. & (2.2) \\
 & \left. \frac{1}{2} \varphi_1 \left(\frac{b_0 z - \tau}{b_0} \right) J_-(b_0 z - \tau) + \frac{1}{2} \varphi_1 \left(\frac{b_0 z + \tau}{b_0} \right) \right] + \\
 & h \int_0^\tau \int_0^\infty (z + y) \exp(-h_1 y) F(\tau - s - \beta_1 y, z + y) \psi(s) dy ds + \\
 & \frac{h}{b_0 + \beta_1} \int_0^\tau F_1(\tau - s, z) J_-(\tau - b_0 z - s) \psi(s) ds + \\
 & \int_0^\tau \int_0^\infty \left[\Phi(\tau - s, |z - \xi|) - \Phi(\tau - s, z + \xi) + \frac{1}{b_0 + \beta_1} \times \right. \\
 & \left. F_1(\tau - s, z + \xi) J_-(\tau - s - b_0(z + \xi)) + \int_0^\infty (z + \xi + y) \times \right. \\
 & \left. \exp(-h_1 y) F(\tau - s - \beta_1 y, z + \xi + y) dy \right] f(\xi, s) d\xi ds + \int_0^\tau \left[\Phi(\tau, \right. \\
 & \left. |z - \xi|) - \Phi(\tau, z + \xi) + \frac{1}{b_0 + \beta_1} F_1(\tau, z + \xi) J_-(\tau - b_0(z + \xi)) + \right. \\
 & \left. \int_0^\infty \exp(-h_1 y) (z + \xi + y) F(\tau - \beta_1 y, z + \xi + y) dy \right] [b_0^2 \varphi_2(\xi) + \\
 & b_1^2 \varphi_1(\xi)] d\xi + b_0^2 \int_0^\infty \left\{ k_1 \left[\Phi(\tau, z + \xi) - \Phi(\tau, |z - \xi|) + \frac{\tau}{2b_0^2} \times \right. \right. \\
 & \left. \left. [F(\tau, |z - \xi|) - F(\tau, z + \xi)] + \left(\frac{k_1^2 b_0}{2} \frac{\tau + \beta_1(z + \xi)}{(\beta_1 + b_0)^2} - \right. \right. \right. \\
 & \left. \left. \frac{k_1 b_0 + h_1}{(b_0 + \beta_1)^2} \right) F_1(\tau, z + \xi) J_-(\tau - b_0(z + \xi)) + \int_0^\infty \exp(-h_1 y) \times \right. \\
 & \left. (z + \xi + y) \left[\frac{2k_1^2 b_0^2 (\tau - \beta_1 y)}{(\tau - \beta_1 y)^2 - b_0^2 (z + \xi + y)^2} \Phi(\tau - \beta_1 y, z + \xi + y) - \right. \right. \\
 & \left. \left. \left(k_1 + 2 \frac{\tau - \beta_1 y}{(\tau - \beta_1 y)^2 - b_0^2 (z + \xi + y)^2} \right) F(\tau - \beta_1 y, z + \xi + y) \right] dy \right\} \varphi_1(\xi) d\xi \\
 F_1(\tau, z) = & \exp\left(\frac{h_1 - k_1 \beta_1}{b_0 + \beta_1} b_0 z\right) \exp\left(-\frac{k_1 b_0 + h_1}{b_0 + \beta_1} \tau\right) \\
 F(\tau, z) = & k_1 b_0 \exp(-k_1 \tau) \frac{I_1(k_1 \sqrt{\tau^2 - b_0^2 z^2})}{\sqrt{\tau^2 - b_0^2 z^2}} J_-(\tau - b_0 z)
 \end{aligned}$$

Proof. Let us rewrite (2.2) as follows:

$$\begin{aligned}
 u(\tau, z) = & -2h \int_0^\tau \int_0^\infty \exp(-h_1 y) \frac{\partial}{\partial z} \Phi(\tau - s - \beta_1 y, z + y) \psi(s) dy ds + \\
 & \int_0^\tau \int_0^\infty \left[\Phi(\tau - s, |z - s|) - \Phi(\tau - s, z + \xi) - 2 \int_0^\infty \exp(-h_1 y) \times \right.
 \end{aligned}$$

$$\begin{aligned} & \frac{\partial}{\partial \xi} \Phi(\tau - s - \beta_1 y, z + \xi + y) dy] f(s, \xi) d\xi ds + b_0^2 \int_0^\infty [\Phi(\tau, |z - \\ & \xi|) - \Phi(\tau, z + \xi) - 2 \int_0^\infty \exp(-h_1 y) \frac{\partial}{\partial \xi} \Phi(\tau - \beta_1 y, z + \xi + y) dy] \times \\ & \varphi_2(\xi) d\xi + \int_0^\infty (b_0^2 \frac{\partial}{\partial \tau} + b_1^2) [\Phi(\tau, |z - \xi|) - \Phi(\tau, z + \xi) - \\ & 2 \int_0^\infty \exp(-h_1 y) \frac{\partial}{\partial \xi} \Phi(\tau - \beta_1 y, z + \xi + y) dy] \varphi_1(\xi) d\xi = \\ & W * \psi(\tau) + E ** f(\tau, z) + K * [\varphi_2(z) + \frac{b_1^2}{b_0^2} \varphi_1(z)] + \frac{\partial K}{\partial \tau} * \varphi_1(z) \end{aligned}$$

The validity of (2.2) becomes evident if we use the properties of the functions W, K and E , theorems on the continuity and differentiability of convolutions [8] taking into account that

$$\left(\frac{\partial^2 K}{\partial \tau^2} * \varphi_1 \right) \Big|_{\tau=0} = \left(\frac{1}{b_0^2} \frac{\partial^2}{\partial z^2} - \frac{b_1^2}{b_0^2} \frac{\partial}{\partial \tau} \right) K \Big|_{\tau=0} = - \frac{b_1^2}{b_0^2} \varphi_1$$

Corollaries. (1). Formula (2.2) defines:

(a) The solution of the mixed problem (2.1) for a boundary condition of the third kind for $\alpha = 1, \beta = 1$;

(b) The solution of the mixed problem (2.1) for a boundary condition of the second kind for $\alpha = 0, h = -1$;

(c) The solution of the mixed problem (2.1) for a boundary condition of the first kind for $h \rightarrow \infty, \beta \rightarrow \infty, \alpha = 1$.

(2°). Formula (2.2) defines the solution of the mixed problem (2.1) for a pure wave equation when $b_1 = 0$, and for the parabolic equation obtained from (2.1) for $b_0 = 0$ when $\beta_1 = 0$ and $b_0 \rightarrow 0$. This latter solution has the form

$$\begin{aligned} u_n &= h \int_0^\tau \int_0^\infty (z + y) \exp(-h_1 y) F_n(\tau - s, z + y) \psi(s) dy ds + \quad (2.3) \\ & \int_0^\tau \int_0^\infty [\Phi_n(\tau - s, |z - \xi|) - \Phi_n(\tau - s, z + \xi) + \int_0^\infty (z + \xi + y) \times \\ & \exp(-h_1 y) F_n(\tau - s, z + \xi + y) dy] f(s, \xi) d\xi ds + \int_0^\infty [\Phi_n(\tau, |z - \\ & \xi|) - \Phi_n(\tau, z + \xi) + \int_0^\infty (z + \xi + y) \exp(-h_1 y) F_n(\tau, z + \xi + y)] b_1^2 \varphi_1(\xi) d\xi \\ \Phi_n &= \lim_{b_0 \rightarrow 0} \Phi(\tau, z) = \frac{1}{2b_1 \sqrt{\pi \tau}} \exp\left(-\frac{b_1^2 z^2}{4\tau}\right) \\ F_n &= \lim_{b_0 \rightarrow 0} F = \frac{b_1}{2 \sqrt{\pi \tau^{3/2}}} \exp\left(-\frac{b_1^2 z^2}{4\tau}\right) \end{aligned}$$

3. The temperature field. Assuming $f = \varphi_1 = \varphi_2 = 0$ in (2.2)

$$\psi(s) = \left(1 + \alpha_1 \frac{\partial}{\partial s} \right) \varphi(s) = \frac{\alpha_0}{\tau_0} \left(1 + \frac{\alpha \tau_r}{\beta} \frac{\partial}{\partial s} \right) [s J_-(s) - (s - \tau_0) J_-(s - \tau_0)]$$

and replacing u by t , we obtain after elementary manipulations

$$\begin{aligned}
 t(\tau, z) = & \frac{\alpha_0 h \exp(-k_1 b_0 z)}{\tau_0 (h_1 + k_1 b_0)} [\Phi_1(\tau, z) J_-(\tau - b_0 z) - \\
 & \Phi_1(\tau - \tau_0, z) J_-(\tau - \tau_0 - b_0 z)] + \frac{\alpha_0 \alpha_1 h k_1^2 b_0 \exp(-k_1 b_0 z)}{\tau_0 (h_1 + k_1 b_0)} \times \\
 & [\Phi_2(\tau, z) J_-(\tau - b_0 z) - \Phi_2(\tau - \tau_0, z) J_-(\tau - \tau_0 - b_0 z)] + \\
 & k_1 b_0 h \frac{\alpha_0}{\tau_0} [\Phi_3(\tau, z) J_-(\tau - b_0 z) - \Phi_3(\tau - \tau_0, z) J_-(\tau - \tau_0 - z b_0)] \equiv \\
 & F_2(\tau, z) J_-(\tau - b_0 z) - F_2(\tau - \tau_0, z) J_-(\tau - \tau_0 - b_0 z) \equiv \\
 & (I - T_{\tau_0}) [F_2(\tau, z) J_-(\tau - b_0 z)]
 \end{aligned} \tag{3.1}$$

Here

$$\begin{aligned}
 \Phi_1(\tau, z) &= \tau - b_0 z - \frac{1 - \alpha_1 d}{d} + \frac{1 - \alpha_1 d}{d} \exp[-d(\tau - b_0 z)] \\
 \Phi_2(\tau, z) &= z(\tau - b_0 z) + \frac{\tau - (2b_0 + \beta_1)z}{h_1 + k_1 b_0} - \frac{2(b_0 + \beta_1)}{(h_1 + k_1 b_0)^2} + \\
 & \exp[-d(\tau - b_0 z)] \left[\frac{\tau + \beta_1 z}{h_1 + k_1 b_0} + \frac{2(b_0 + \beta_1)}{(h_1 + k_1 b_0)^2} \right] \\
 \Phi_3(\tau, z) &= \int_0^{\tau_1} \int_0^{v_1} (z + y) \exp[-h_1 y - k_1(\tau - s - \beta_1 y)] \left\{ \left[1 - \alpha_1 k_1 - \right. \right. \\
 & \left. \left. \frac{2\alpha_1(\tau - s - \beta_1 y)}{(\tau - s - \beta_1 y)^2 - b_0^2(z + y)^2} \right] \frac{I_1(k_1 \sqrt{(\tau - s - \beta_1 y)^2 - b_0^2(z + y)^2})}{\sqrt{(\tau - s - \beta_1 y)^2 - b_0^2(z + y)^2}} + \right. \\
 & \left. \frac{k_1 \alpha_1 (\tau - s - \beta_1 y)}{(\tau - s - \beta_1 y)^2 - b_0^2(z + y)^2} \times \right. \\
 & \left. I_0(k_1 \sqrt{(\tau - s - \beta_1 y)^2 - b_0^2(z + y)^2}) \right\} s dy ds \\
 \alpha_1 &= \beta^{-1} \alpha \tau, \quad d = (b_0 + \beta_1)^{-1} (h_1 + k_1 b_0), \quad h_1 = \alpha h, \quad \beta_1 = \alpha_1 h \\
 \tau_1 &= \tau - b_0 z, \quad v_1 = (b_0 + \beta_1)^{-1} (\tau - b_0 z - s)
 \end{aligned}$$

The function $t(z, \tau)$ defined by (3.1) for $\alpha = \beta = 1$ describes the desired temperature field in the elastic half-space $z \geq 0$.

If the temperature or heat flux is specified on the boundary of the elastic half-space, then the temperature field has the form (3.1), where the functions

$$\begin{aligned}
 F_3(\tau, z) &= \lim_{\substack{\beta \rightarrow \infty \\ h \rightarrow \infty}} F_2(\tau, z) |_{\alpha=1} = \frac{\alpha_0}{\tau_0} \left[(\tau - b_0 z) \exp(-k_1 b_0 z) + \right. \\
 & \left. k_1 b_0 z \int_{b_0 z}^{\tau} (\tau - \xi) \exp(-k_1 \xi) \frac{I_1(k_1 \sqrt{\xi^2 - b_0^2 z^2})}{\sqrt{\xi^2 - b_0^2 z^2}} d\xi \right] \\
 F_4(\tau, z) &= \lim_{\alpha \rightarrow 0} F_2(\tau, z) |_{h=-1} = \frac{\alpha_0}{b_0 \tau_0} \times \\
 & \int_0^{\tau_1} s \exp(-k_1(\tau - s)) I_0(k_1 \sqrt{(\tau - s)^2 - b_0^2 z^2}) ds
 \end{aligned}$$

must, respectively, replace $F_2(\tau, z)$.

The case of a jump change in the temperature on the boundary of an elastic half-space can be obtained from (3.1) with $\tau_0 \rightarrow 0$. Thus, (3.1) includes all the boundary conditions occurring most frequently in practice. Let us note that for $b_0 \rightarrow 0$ we obtain the

corresponding parabolic (usual) temperature fields, and for $b_1 = 0$ the pure wave temperature fields satisfying conditions specified on the boundary.

4. The stress field. In (2.2) let us set

$$\varphi_1 = \varphi_2 = \psi = 0, \alpha = 1, b_0^2 = \frac{1}{c^2}, b_1^2 = 0, f(s, \xi) = -a \frac{\partial^2 t(s, \xi)}{\partial s^2}, u = \sigma_z$$

Then letting $h \rightarrow \infty, \beta \rightarrow \infty$, we obtain that the stress field in an elastic half-space is described by the functions (all the shear stresses equal zero)

$$\begin{aligned} \sigma_z(\tau, z) &= \frac{ac}{2} \int_0^{\tau} \int_0^{\infty} \left[J_- \left(\tau - s - \frac{z - \xi}{c} \right) - J_- \left(\tau - s - \frac{|z - \xi|}{c} \right) \right] \times \quad (4.1) \\ &\frac{\partial^2 t}{\partial s^2} d\xi ds = \frac{ac}{2} \left[\int_0^{c\tau - z} \frac{\partial t}{\partial s} \Big|_{s=\tau - z + \xi/c} d\xi J_- \left(\tau - \frac{z}{c} \right) - \right. \\ &\int_z^{c\tau + z} \frac{\partial t}{\partial s} \Big|_{s=\tau + z - \xi/c} d\xi - \int_0^z J_- \left(\tau - \frac{z - \xi}{c} \right) \frac{\partial t}{\partial s} \Big|_{s=\tau - z - \xi/c} d\xi \Big] = \\ &\frac{ac}{2} (1 - T_{\tau^0}) \left[J_- \left(\tau - \frac{z}{c} \right) \int_0^{c\tau - z} F_5 \left(\tau - \frac{z + \xi}{c}, \xi \right) d\xi - \right. \\ &\left. \int_z^{c\tau + z} F_5 \left(\tau + \frac{z - \xi}{c}, \xi \right) d\xi - \int_0^z J_- \left(\tau - \frac{z - \xi}{c} \right) F_5 \left(\tau - \frac{z - \xi}{c}, \xi \right) d\xi \right] \\ \sigma_x = \sigma_y &= \frac{\mu}{1 - \mu} \sigma_z - \frac{E\alpha_{\tau}}{1 - \mu} t(\tau, z) \end{aligned}$$

Here

$$\begin{aligned} F_5 &= \frac{\alpha_0}{\tau_0} J_- (s - b_0 \xi) \left[\frac{h \exp(-k_1 b_0 \xi)}{h_1 + k_1 b_0} \Phi_4(s, \xi) + \right. \\ &\left. \frac{\alpha_1 h k_1^2 b_0}{h_1 + k_1 b_0} \exp(-k_1 b_0 \xi) \Phi_5(s, \xi) + k_1 b_0 h \Phi_6(s, \xi) \right] \\ \Phi_4(s, \xi) &= 1 - (1 - \alpha_1 d) \exp[-d(s - b_0 \xi)] \\ \Phi_5(s, \xi) &= \xi + \frac{1}{h_1 + k_1 b_0} \left\{ 1 - \exp[-d(s - b_0 \xi)] - \right. \\ &\left. \frac{s + \beta_1 \xi}{b_0 + \beta_1} \exp[-d(s - b_0 \xi)] \right\} \\ \Phi_6(s, \xi) &= \int_0^{s_1} \left\{ \left[1 - \alpha_1 k_1 + \frac{\alpha_1 k_1^2 b_0 (s - \eta + \beta_1 \xi)}{4(b_0 + \beta_1)} \right] \frac{k_1 (s - \eta + \beta_1 \xi)}{2(b_0 + \beta_1)^2} \times \right. \\ &\left. \exp \left[-h_1 \frac{s - \eta - b_0 \xi}{b_0 + \beta_1} - k_1 b_0 \frac{s - \eta + \beta_1 \xi}{b_0 + \beta_1} \right] \right\} \eta d\eta + \int_0^{s_1} \int_0^{v_2} (\xi + y) \times \\ &\exp[-h_1 y - k_1 (s - \eta - \beta_1 y)] \left\{ \psi_1(s - \eta - \beta_1 y, \xi + y) I_0 \times \right. \\ &\left. (k_1 \sqrt{(s - \eta - \beta_1 y)^2 + b_0^2 (\xi + y)^2}) + \psi_2(s - \eta - \beta_1 y, \xi + y) \times \right. \\ &\left. \frac{I_1(k_1 \sqrt{(s - \eta - \beta_1 y)^2 + b_0^2 (\xi + y)^2})}{\sqrt{(s - \eta - \beta_1 y)^2 + b_0^2 (\xi + y)^2}} \right\} dy d\eta \\ \psi_1(x, y) &= \frac{k_1}{x^2 - b_0^2 y^2} \left(x - 2\alpha_1 k_1 x - \frac{b_0^2 y^2 + 3x^2}{x^2 - b_0^2 y^2} \alpha_1 \right) \end{aligned}$$

$$\psi_2(x, y) = k_1(a_1 k_1 - 1) + \frac{4\alpha_1 k_1 x - 2x + \alpha_1 k_1^2 x^2}{x^2 - b_1^2 y^2} + 2 \frac{3\alpha_1 x^2 + \alpha_1 b_0^2 y^2}{(x^2 - b_0^2 y^2)^2}$$

$$s_1 = s - b_0 \xi, \quad v_2 = (b_0 + \beta_1)^{-1} (s - \eta - b_0 \xi)$$

where $t(\tau, z)$ is defined by (3.1).

The desired stress field in the half-space has the structure (3.1) for $\alpha = \beta = 1$, i. e.

$$\sigma_z = (I - T_{\tau^{\tau_0}}) \left[F_6(\tau, z) J_- \left(\tau - \frac{z}{c} \right) + F_7(\tau, z) J_-(\tau - b_0 z) \right] \quad (4.2)$$

and analogously for σ_x and σ_y .

Thus, the stress field in an elastic half-space $z \geq 0$ is obtained by the superposition of four kinds of waves: a heat wave with velocity $b_0 = 1/\omega_r$, a sound wave with velocity c , and the same waves but retarded by τ_0 . In contrast to the parabolic case, the stress field is hence continuous.

Let us consider in greater detail the case when a thermal impact with a finite rate of change of the temperature is realized on the boundary of an elastic half-space. In this case the wave function F_5 is

$$F_5(s, \xi) = \frac{\alpha_0}{\tau_0} J_-(s - b_0 \xi) \left[\exp(-k_1 b_0 \xi) + k_1 b_0 \xi \int_{b_0 \xi}^s \exp(-k_1 z) \frac{I_1(k_1 \sqrt{z^2 - b_0^2 \xi^2})}{\sqrt{z^2 - b_0^2 \xi^2}} dz \right] \quad (4.3)$$

Substituting (4.3) into (4.1), we obtain after evident manipulations that the stresses in the elastic half-space are described by the functions

$$\sigma_z = \frac{\alpha \alpha_0}{b_1^2 \tau_0^2} (I - T_{\tau^{\tau_0}}) \left\{ J_- \left(\tau - \frac{z}{c} \right) \left[\exp \left(-k \left(\tau - \frac{z}{c} \right) \right) - 1 \right] + J_-(\tau - b_0 z) [\exp(-k_1 b_0 z) - \exp(-k_1 b_0 z - k(\tau - b_0 z))] + k_1 b_0 z J_-(\tau - b_0 z) \int_{b_0 z}^{\tau} \exp(-k_1 \xi) \times \frac{I_1(k_1 \sqrt{\xi^2 - b_0^2 z^2})}{\sqrt{\xi^2 - b_0^2 z^2}} (1 - \exp(-k(\tau - \xi))) d\xi \right\}$$

$$\sigma_x = \sigma_y = \frac{\mu}{1 - \mu} \sigma_z - \frac{F \alpha_z}{1 - \mu} t, \quad k = \frac{b_1^2 c^2}{b_0^2 c^2 - 1} > 0$$

The quantity t is determined by (3.1), where F_2 is replaced by $F_3(\tau, z)$, and all the shear stresses are zero.

The following corollaries can be obtained from (4.4).

(1). If the temperature field is a pure wave one ($b_1 = 0$), then

$$\sigma_z = \frac{\alpha \alpha_0 c^2}{\tau_0 (b_0^2 c^2 - 1)} (I - T_{\tau^{\tau_0}}) \left[(\tau - b_0 z) J_-(\tau - b_0 z) - \left(\tau - \frac{z}{c} \right) J_- \left(\tau - \frac{z}{c} \right) \right]$$

i. e. the stress field is linear in both time and the space variable.

(2). If a jump thermal impact is realized on the boundary of the elastic half-space, i. e. $\tau_0 \rightarrow 0$, then

$$\sigma_z = \frac{\alpha \alpha_0 c^2}{b_0^2 c^2 - 1} \left\{ \left[\exp(-k_1 b_0 z - k(\tau - b_0 z)) + k_1 b_0 z \times \right. \right. \quad (4.5)$$

$$\int_{b_0 z}^{\tau} \exp(-k\tau - k_1 \xi + k\xi) \frac{I_1(k_1 \sqrt{\xi^2 - b_0^2 z^2})}{\sqrt{\xi^2 - b_0^2 z^2}} d\xi \Big] \times$$

$$J_-(\tau - b_0 z) - J_-\left(\tau - \frac{z}{c}\right) \exp\left[-k\left(\tau - \frac{z}{c}\right)\right]$$

(3). If the velocities of the thermal and elastic wave motions agree ($b_0 = 1/c$), then

$$\sigma_z = \frac{\alpha\alpha_0}{\tau_0 b_1^2} (I - T_{\tau_0}) \left\{ J_-\left(\tau - \frac{z}{c}\right) \left[\exp\left(-\frac{1}{2} b_1^2 c z\right) - \right. \right.$$

$$\left. \left. 1 + \frac{1}{2} b_1^2 c z \int_{z/c}^{\tau} \exp\left(-\frac{1}{2} b_1^2 c^2 \xi\right) \frac{I_1(1/2 b_1^2 c^2 \sqrt{\xi^2 - c^{-2} z^2})}{\sqrt{\xi^2 - c^{-2} z^2}} d\xi \right] \right\}$$

(4). If the temperature field is a pure wave field and the velocities of the thermal and elastic waves agree ($b_1 = 0, b_0 = 1/c$), then the stress field is linear in the space variable

$$\sigma_z = \frac{1}{2} \frac{ca\alpha_0}{\tau_0} z \left[J_-\left(\tau - \tau_0 - \frac{z}{c}\right) - J_-\left(\tau - \frac{z}{c}\right) \right]$$

and exists during the time $\tau \in (z/c, z/c + \tau_0)$. In the case of a thermal impact ($\tau_0 \rightarrow 0$), the stress σ_z acts at a concentrated time (instantaneously)

$$\sigma_z = -\frac{1}{2} ca\alpha_0 z \delta(\tau - z/c)$$

(5). For $b_0 \rightarrow 0$ we obtain the case of the parabolic temperature field considered in [2] from (4.4).

If the heat flux on the boundary of an elastic half-space varies linearly, then the stress field is

$$\sigma_z = \frac{a\alpha_0}{2b_0\tau_0} (I - T_{\tau_0}) \left\{ J_-\left(\tau - \frac{z}{c}\right) \left[\int_0^{\tau_2} \int_{b_0 \xi_2}^{\xi_1} \exp(-k\xi) I_0(q) ds d\xi - \right. \right. \tag{4.6}$$

$$\left. \int_0^{\tau_3} \int_{b_0 \xi_3}^{\xi_4} \exp(-ks) I_0(q) ds d\xi \right] + J_-(\tau - b_0 z) \left[\int_z^{\tau_4} \int_{b_0 \xi_4}^{\xi_3} \exp(-k_1 s) \times \right.$$

$$\left. I_0(q) ds d\xi - \int_z^{\tau_5} \int_{b_0 \xi_5}^{\xi_1} \exp(-k_1 s) I_0(q) ds d\xi \right] \Big\}$$

$$q = k_1 \sqrt{s^2 - b_0^2 \xi^2}, \quad \tau_2 = \frac{c\tau - z}{cb_0 - 1}, \quad \tau_3 = \frac{c\tau - z}{cb_0 + 1}, \quad \tau_4 = \frac{c\tau + z}{cb_0 + 1}$$

$$\xi_1 = c^{-1}(c\tau - z + \xi), \quad \xi_2 = c^{-1}(c\tau - z - \xi), \quad \xi_3 = \tau + c^{-1}(z - \xi)$$

Evidently corollaries analogous to those obtained from (4.4) can be obtained from (4.6).

Graphs of the dependence of the stress $\bar{\sigma}_z = A^{-1} \sigma_z$ ($A = b_1^{-2} a \alpha_0$) on the time τ in

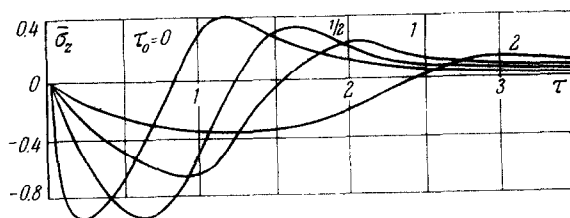


Fig. 1

the section $\xi = 1$ ($\xi = b_0 z$) for different heating times τ_0 have been constructed for a steel half-space by means of (4.4), (4.5).

It is seen from Fig. 1 that the maximum stress diminishes rapidly as τ_0 increases, and for $\tau_0 = 2$ this maximum is around 43% of its value at $\tau_0 = 0$ (instantaneous heating). Thus, the maximum dynamic stress is reduced 57% for a 2 sec heating duration. This indicates that taking account of the finite velocity of heat propagation, the rise in stress due to dynamic effects generally has no practical value.

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ON THE EXISTENCE OF A FIELD OF STRESS RATES
IN A HARDENING ELASTIC-PLASTIC MEDIUM

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The boundary value problem for the stress rates and rates of change fields in the quasi-static motion of a volume V of an elastic-plastic medium [1] consists of finding the pairs $\dot{\sigma}_{ij}$, $\dot{\epsilon}_{ij}$ related by the governing equations of an appropriate model; here the $\dot{\sigma}_{ij}$ should be statically admissible, i. e. should satisfy the equations and boundary conditions

$$\dot{\sigma}_{ij,j} = -X_i, \quad \dot{\sigma}_{ij} n_j |_{S_p} = p_i \quad (0.1)$$

and $\dot{\epsilon}_{ij}$ should be kinematically admissible, i. e. $2\dot{\epsilon}_{ij} = v_{i,j} + v_{j,i}$, where

$$v_i |_{S_u} = \dot{u}_{i0} \quad (0.2)$$

Here S_p and S_u are nonintersecting parts of the boundary of the volume V , X_i , p_i , u_{i0} are specified functions. The question of the existence of a solution of this problem reduces to the question of the functional